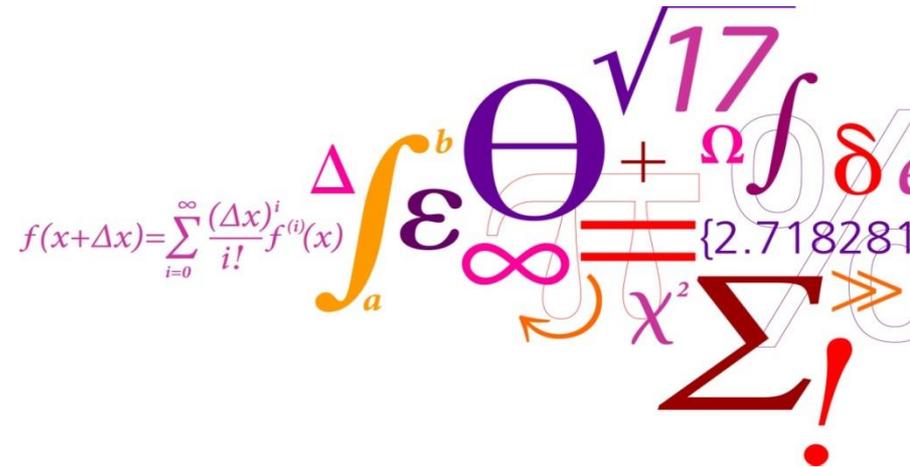


# Research scanners at CFU

by Borislav Tomov,  
CFU



$$f(x+\Delta x) = \sum_{i=0}^{\infty} \frac{(\Delta x)^i}{i!} f^{(i)}(x)$$

Other symbols visible:  $\int_a^b$ ,  $\epsilon$ ,  $\Theta$ ,  $\sqrt{17}$ ,  $+$ ,  $\Omega$ ,  $\int$ ,  $\delta$ ,  $\infty$ ,  $\chi^2$ ,  $\Sigma$ ,  $\gg$ ,  $\{2.718281\}$ , and an exclamation mark.

# Why

- Commercial scanner : video out
- Comm. scanner + research interface : RF BF data
- Research scanner: full access to setup and RF channel data



# How

- Setup of emission sequences (frames)
- Setup of transmit
- Setup of receive
- Setup of image processing/navigation

# 2-channel sampling system (1991)

ADC:  
20MHz  
12-bit

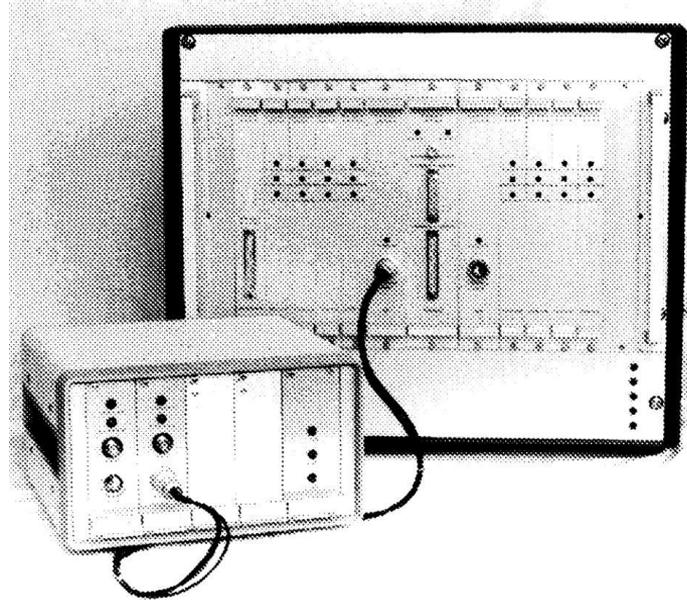
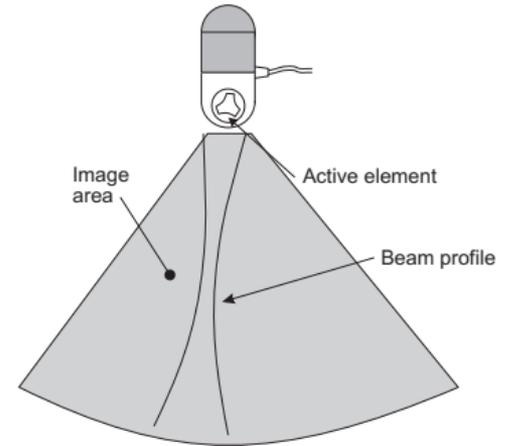


Photo out of paper by Jensen/Mathorhe, 1991

Sector scan transducer

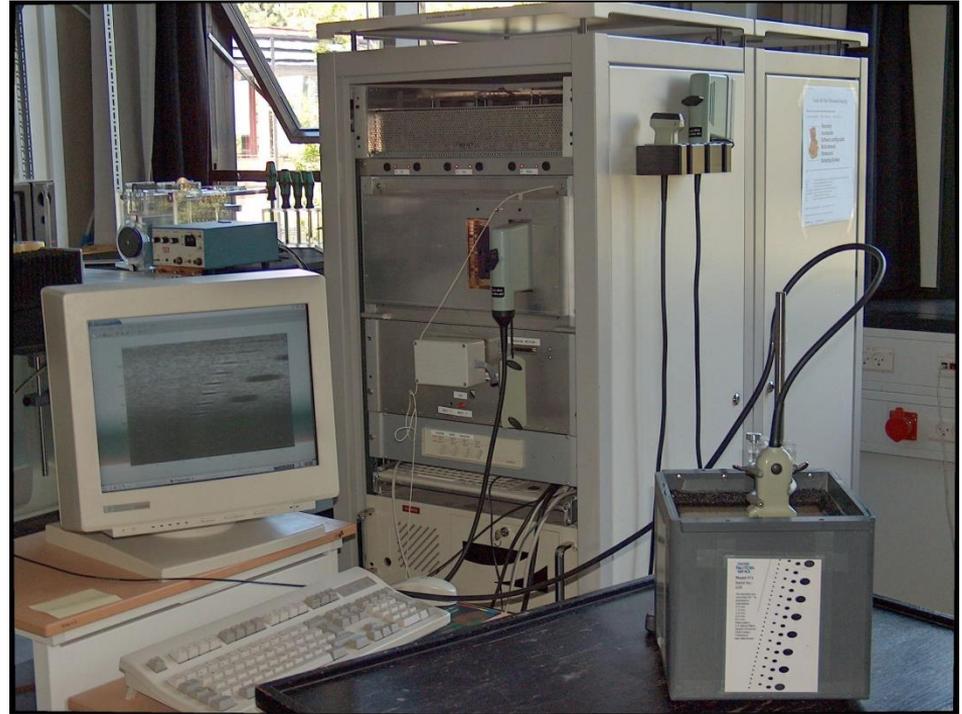


Drawing by J. A. Jensen, 1996

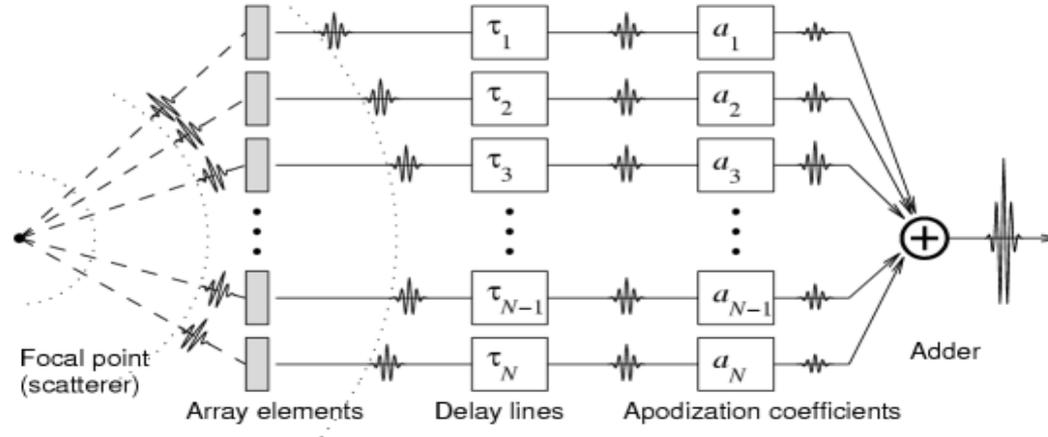
# RASMUS (2001)



Remotely  
Accessible  
Software programmable  
Multi-channel  
Ultrasound  
System



# Purpose of RASMUS



- Flexible transmission
- Storage of data for later experimental beamforming
- Real time processing and imaging for orientation

# Block diagram

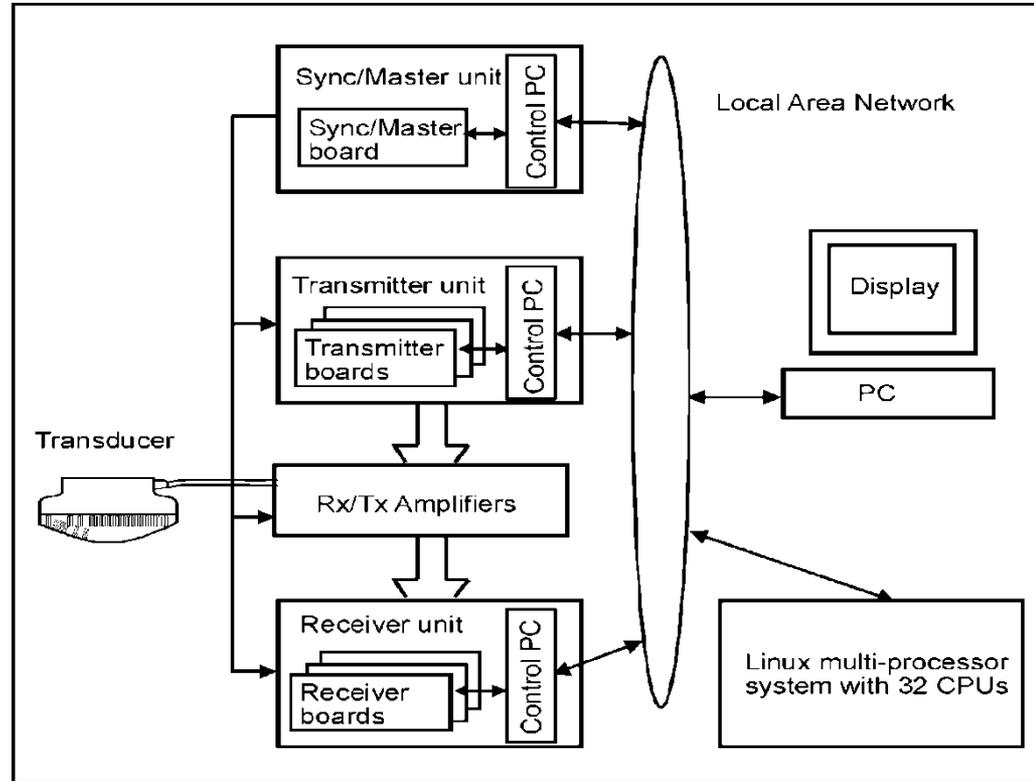


Diagram out of paper by Jensen et al., 1999

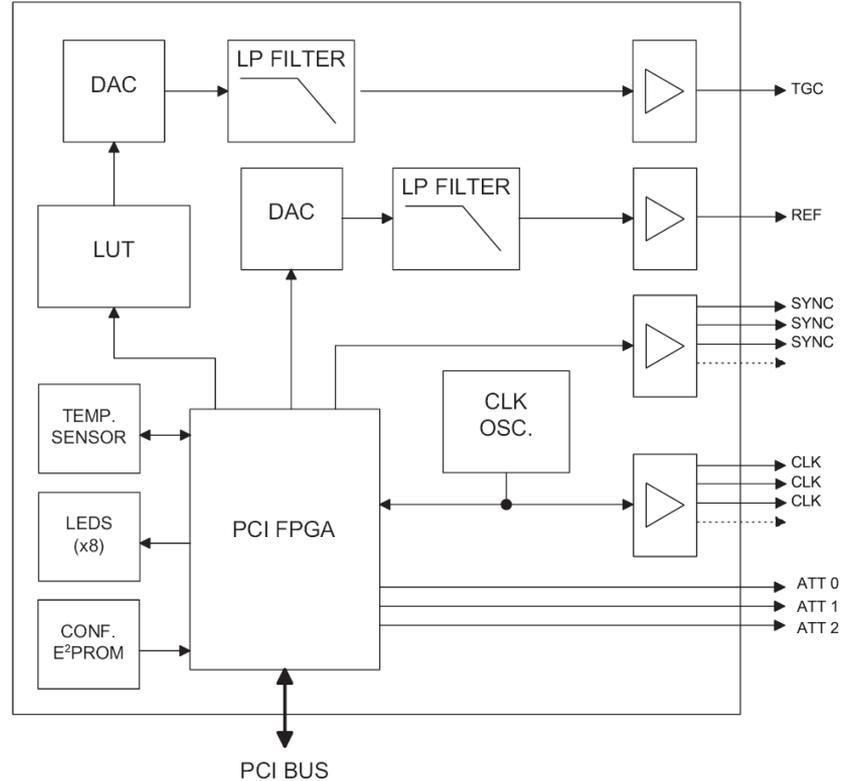
# Construction



Photo by J.A. Jensen, 2002

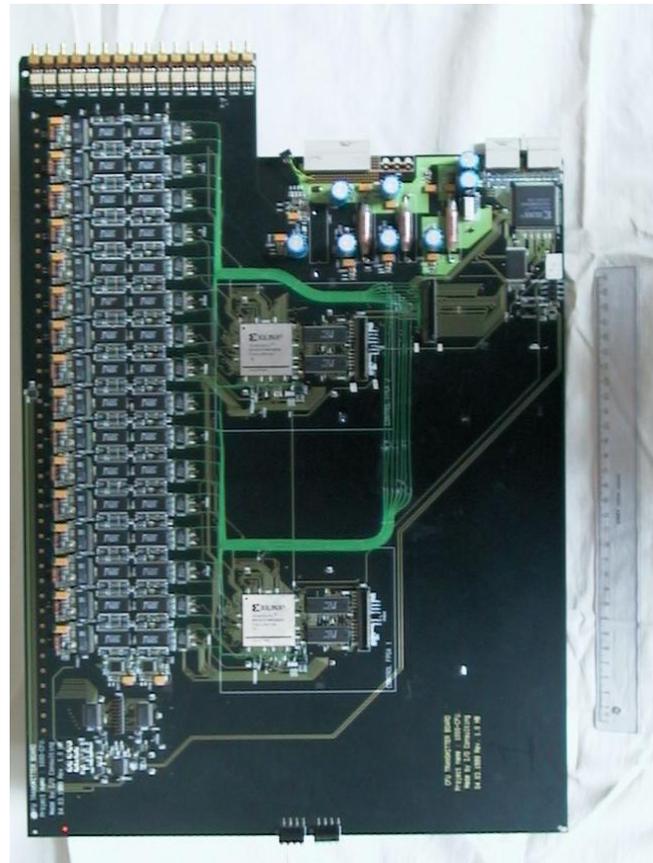


# Timing board

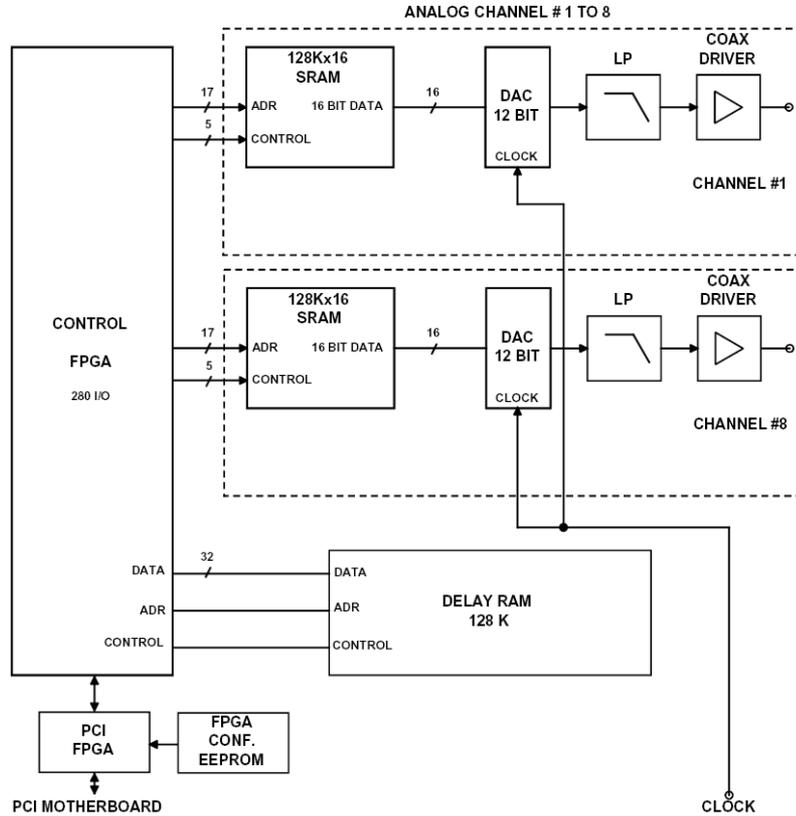


# Transmitter boards

- DAC: 40 MHz, 12-bit
- 256 kB per channel waveform RAM
- Independent waveforms for each channel and emission
- 16 channels/board
- 128 channels in total



# Transmitter boards

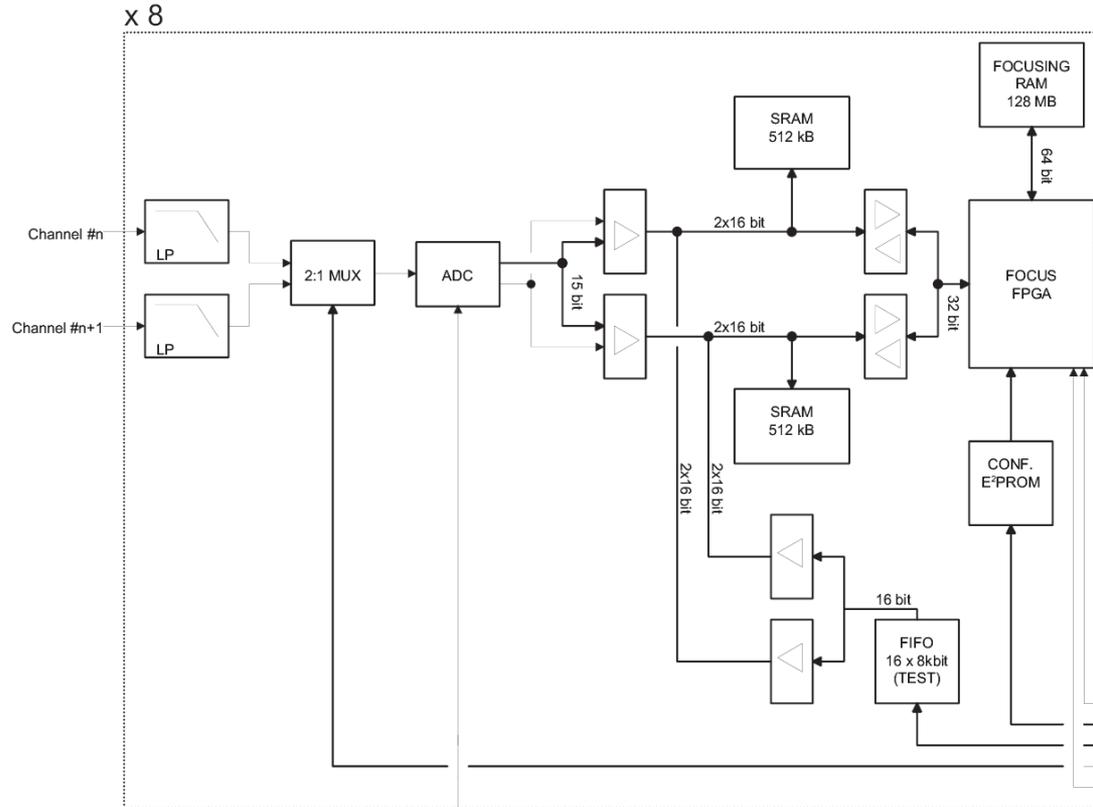


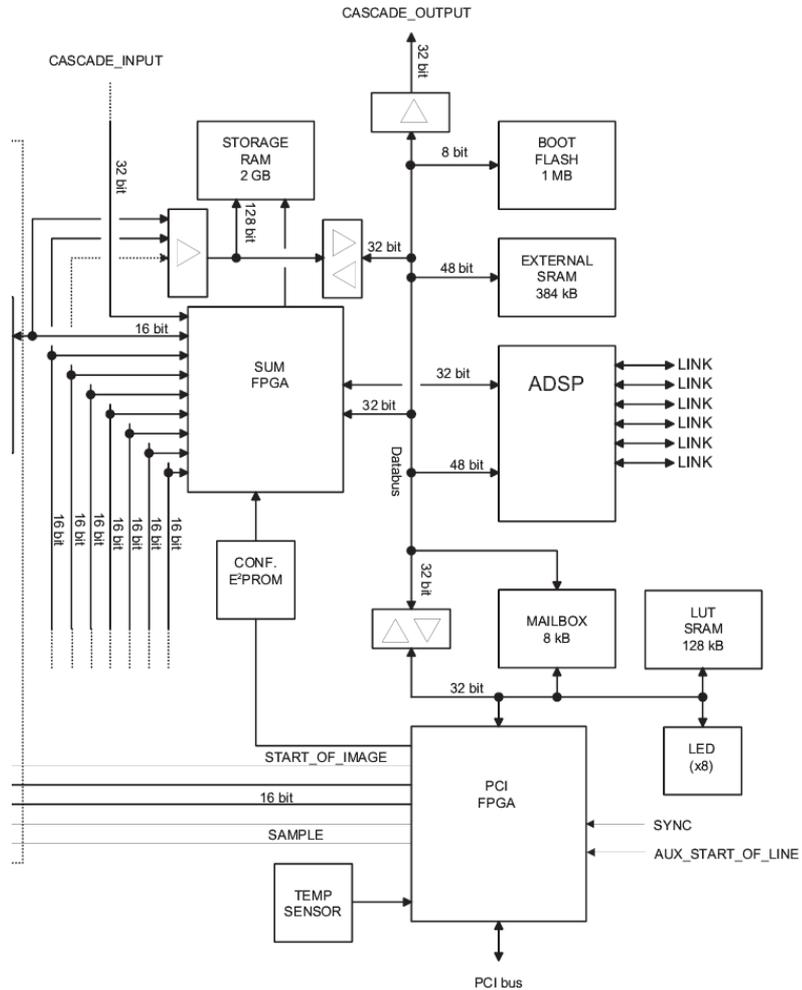
# Receiver boards

- 8 channels per board
- 2-to-1 multiplexing
- ADC: 40 MHz, 12-bit
- 256 MB RAM per channel (3 seconds of real time data, 2 GB)



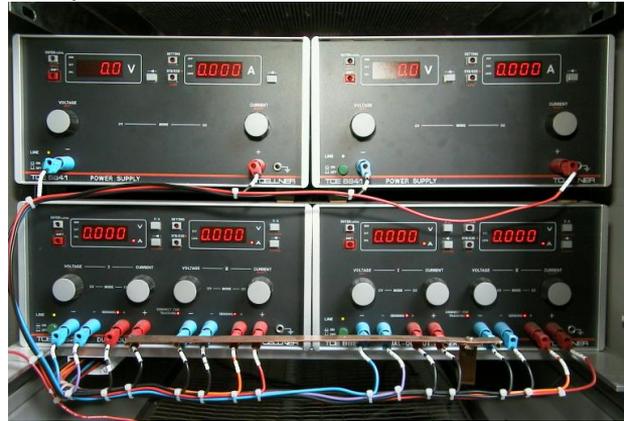
# Receiver boards





# Power supplies

-50 V      Start these last and together, stop first      + 50 V



+5 V, -5 V

+15 V, -15 V

# Outline-software

- Organization
- Commands
  - Initialization and closing
  - Setup - general commands
  - Setup - timing board
  - Setup - transmitter
  - Setup - receiver
  - Acquisition
  - Reading data

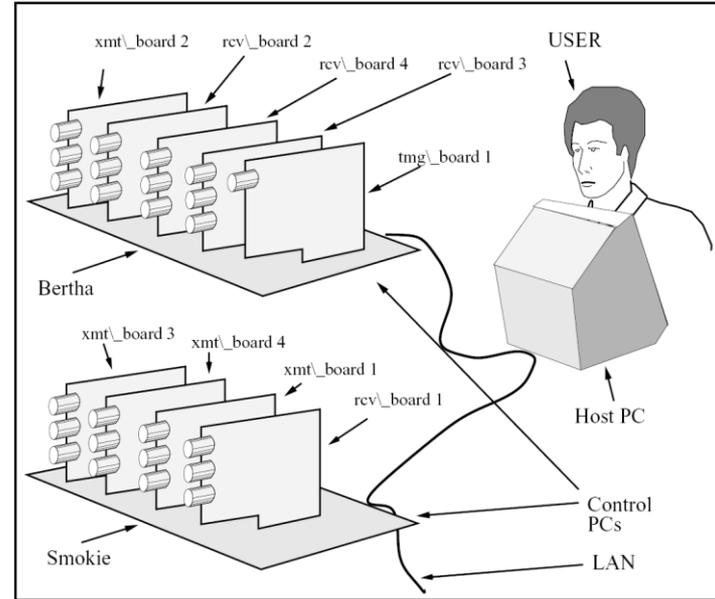
# Software organization

## Host PC:

- user sits at it
- runs Matlab
- C library functions called from Matlab

## Control PC:

- contains RASMUS boards
- runs drivers
- runs execution server "sys\_master\_ctrl"



# Initialization and closing

```
sys_init([file_name, [show_logo,[interrupt]]])
```

- Uses `/home/username/.syslib` by default

```
sys_end
```

- Releases the command server for other users and the memory used by Matlab

```
sys_abort
```

- Stops the command server

## Setup - general

`sys_set_param(parameter_name, parameter_value)`

- For now, **c** and **f<sub>s</sub>** (default 1540 and 40e6)

`sys_set_no_lines(number_lines [, skipped, sampled])`

`sys_set_sampling_interval(start_depth, end_depth)`

`sys_set_fprf(pulse_repetition_frequency)`

`tr_bk8802, tr_bk8804, tr_general, xmt_set_no_samples(n)`

# Setup-timing board

tmg\_ref\_voltage(*voltage*)

- reference voltage for the TGC amplifiers

tmg\_set\_attn(*attenuation \_code*)

- attenuation of the transmit amplifiers.

tmg\_tgc2(*gain\_values*)

- 0 to 48 (in dB), 1 value per microsecond

## Setup- transmitter

`xmt_set_ref_v(voltage)`

`xmt_center_focus(line_numbers,point_coordinates [, frame_no])`

`xmt_focus(line_numbers,point_coordinates [, frame_no])`

`xmt_excitation(samples_normalized)`

`xmt_apodization(line_no, apodization [, frame_no])`

`xmt_mode(continuous_mode, use_external_trigger)`

## Setup-receiver

`rcv_center_focus(line_numbers, point_coordinates)`

`rcv_focus(line_no, switch_pos, times, focal_points)`

`rcv_dynamic_focus (line_no, switch_pos, time, angle_xz, angle_yz)`

`rcv_apodization (line_no, times, values)`

`rcv_mode(...)`

# Acquisition

```
tmg_measure(no_images)
```

# Reading data

`rcv_get_current_image(brd_no)`

`rcv_set_current_image(offset, relative)`

`rcv_storage_read_sampled(channel_numbers, image_no, line_no,  
to_double)`

`rcv_storage_read_summed(board_no, image_no, lines_no,  
'class_name')`

# 2001 - Rasmine

Transmitter board    Sampling board    PCs



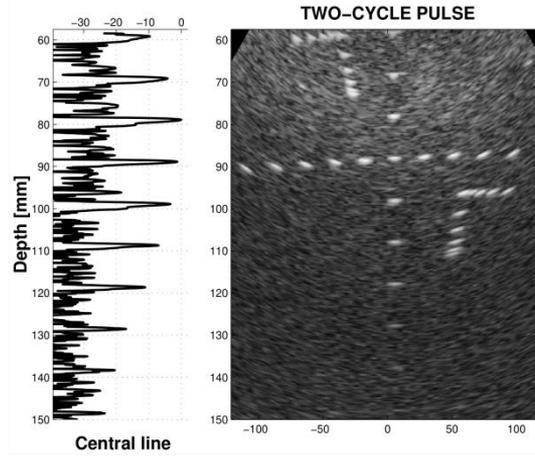
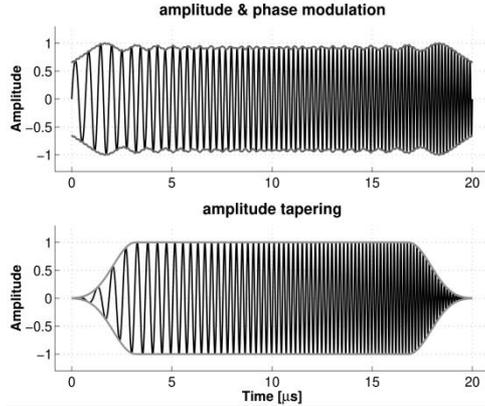
Wire phantom

Amplifier

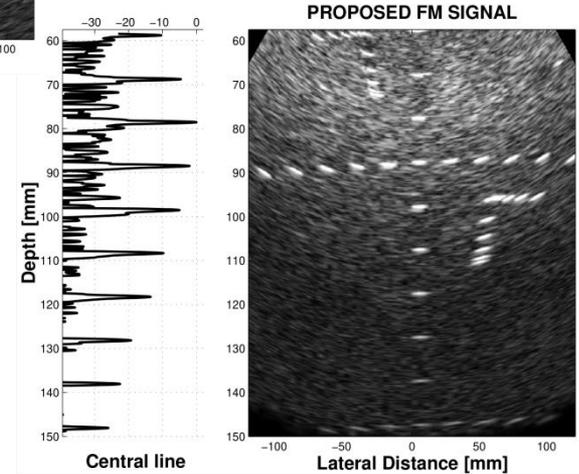
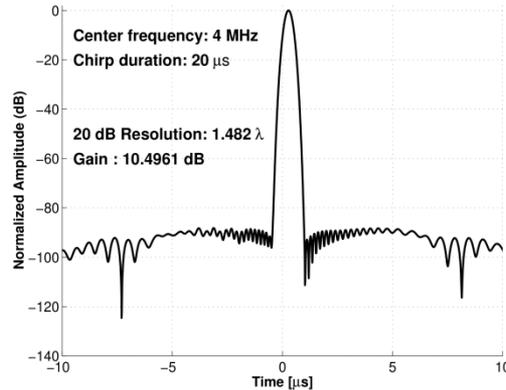
US scanner

Photo by Thanassis  
Misaridis,  
2001

# Rasmine - results



Research by T. Misaridis (1999,2000)



# SARUS (2010)

Synthetic  
Aperture  
Real-time  
Ultrasound imaging  
System



# Purpose of SARUS

- It is an experimental ultrasound imaging system:
  - Flexible transmit side – 1024 independent channels, up to 4096 samples at 70 MHz, up to 8192 different excitations per channel
  - Flexible receive side – selective sampling on 0 to 16 channels per board (0, 4 or higher even numbers), 1024 channels in total, 1 second continuous sampling at 70 MHz
  - Real-time preview / navigation capability - also using SA imaging
  - Transportable

# Architecture

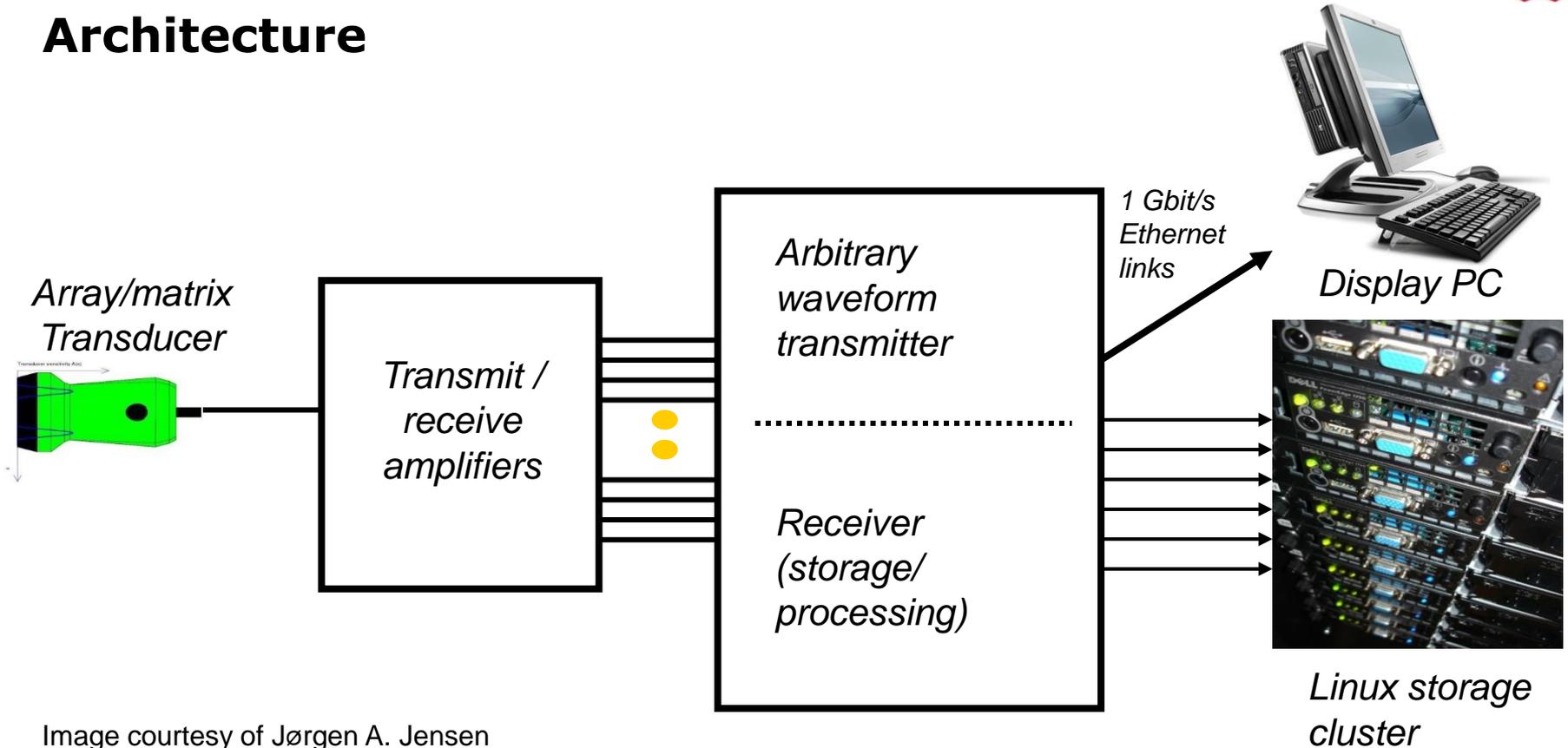
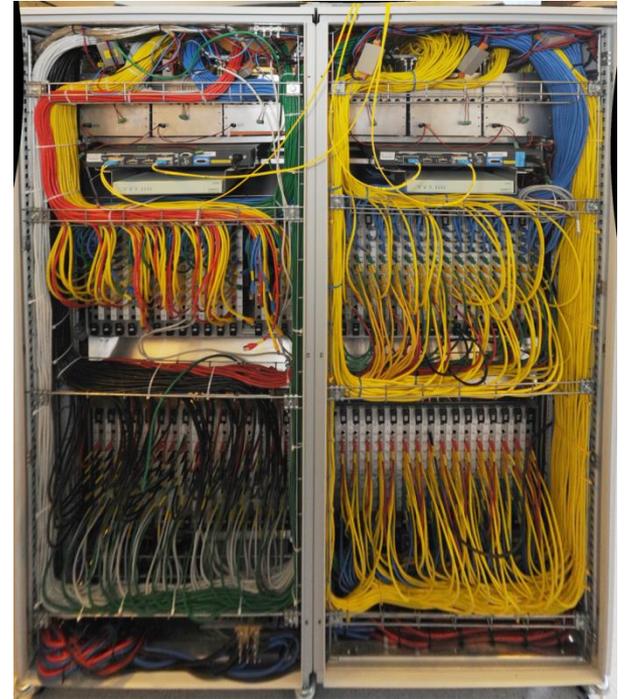
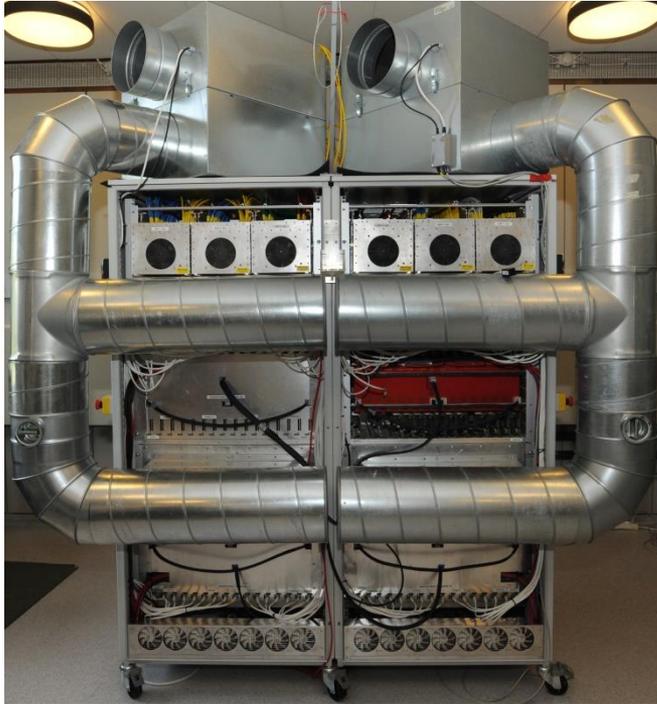


Image courtesy of Jørgen A. Jensen

# Hardware components

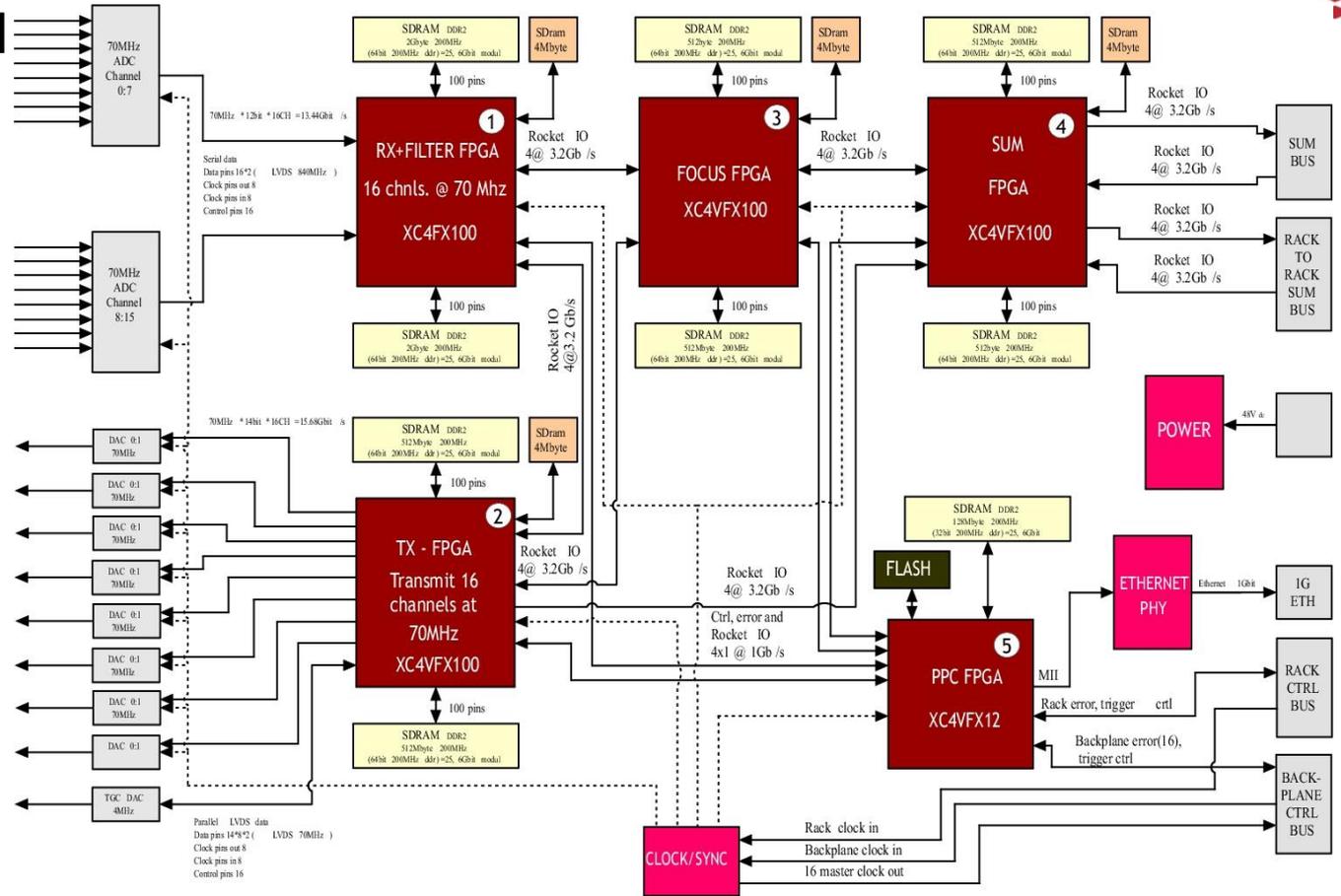
- Digital acquisition / processing boards
  - 64 boards x 16 channels, 1 board is timing ctrl
  - Distributed in 4 racks / 2 cabinets
- Transmit / receive amplifiers
  - 128 amplifier boards in 6 boxes, up to 24 brd. per box
- 6 B-K transducer connectors ( 5 x 192 ch. and 1 x 64 ch.)
- Cabling – 512 cables

# Initial cooling setup

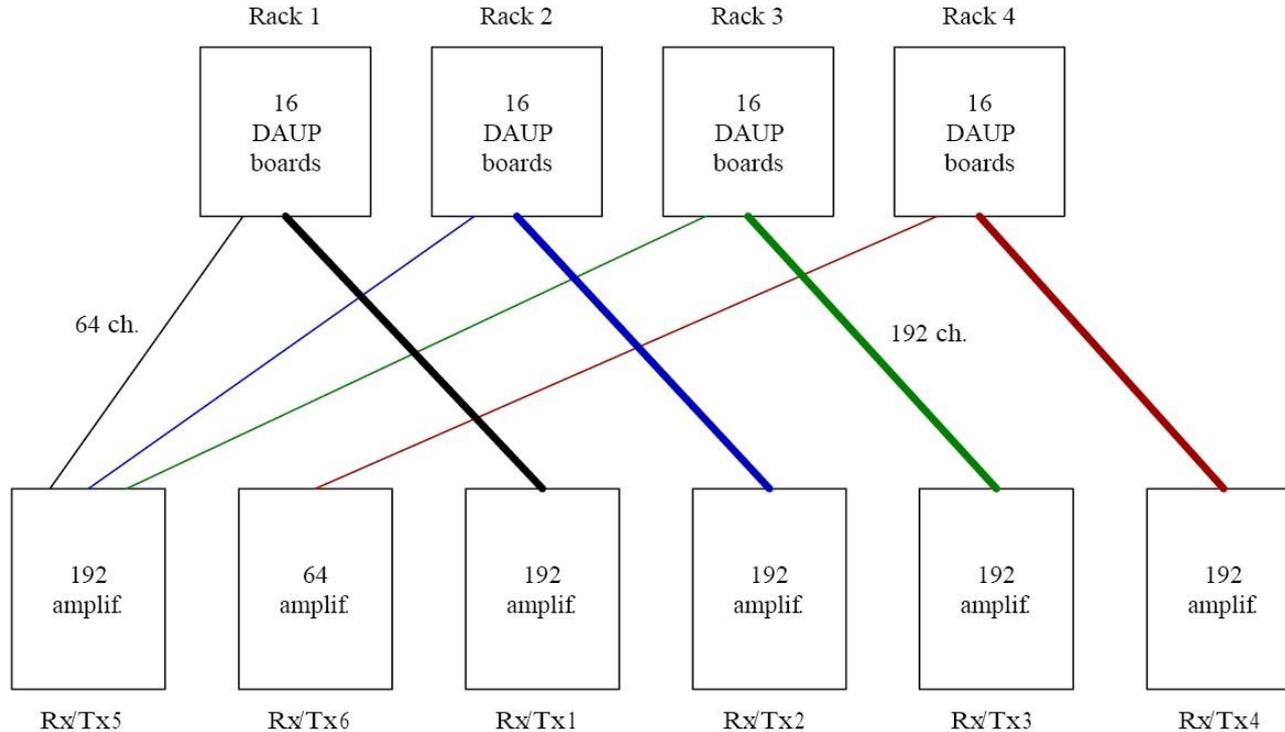


Photos by M. F. Rasmussen, 2012

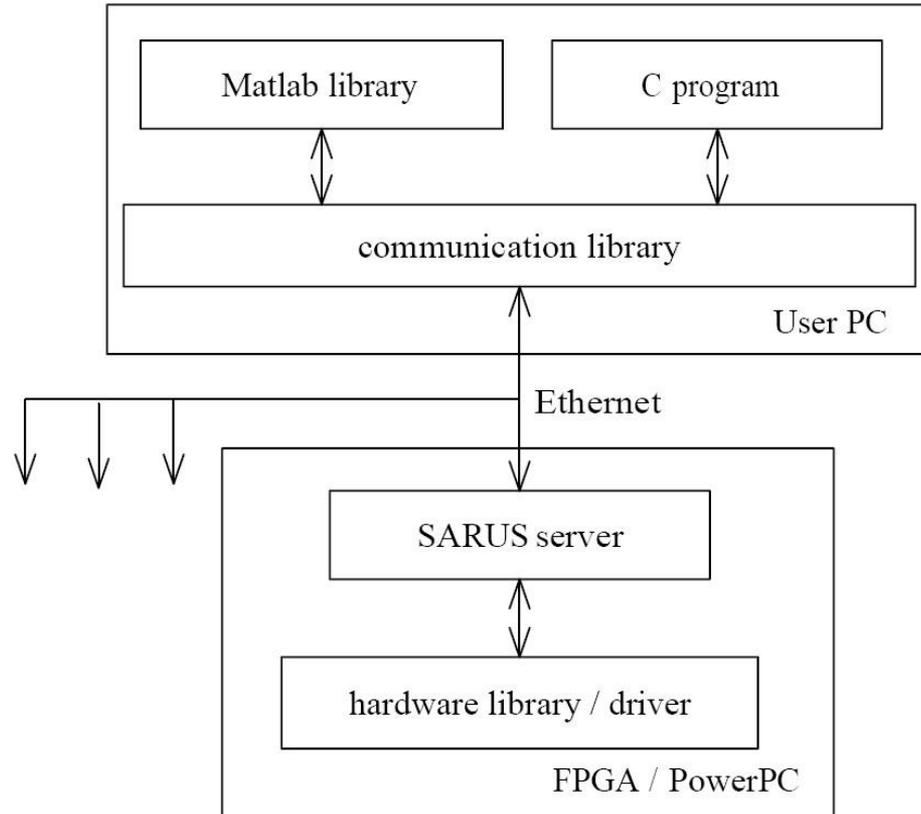
# DAUP board



# Cable connections



# Software structure



# Concepts/terms

- **Image** – a pretty picture for display, made of **lines**
- An **emission** provides data for one image **line**, or for a whole low-resolution **image** in SA imaging.
- **Frame** – a set of **emissions** that accomplish the task of providing data for a B-mode image, color flow map, etc.
- A **sequence** is made of **frames** in a chain  
/// nowadays, people call a frame **sequence**

# General SARUS commands

- *sarus\_init(file\_name)*
- *sarus\_end*
- *sarus\_clear*
- *sarus\_reset\_fpgas*

# Geometry and timing setup commands

- *sarus\_use\_transducer(xdc\_name, serial\_num, flags)*
- *sarus\_set\_speed\_of\_sound(c)*
- *sarus\_create\_frame(no\_emissions[,...] )*
- *sarus\_set\_tprf(tprf\_array)*
- *sarus\_set\_fprf(fprf\_scalar)*

# Transmitter setup using virtual sources

- *sarus\_xmt\_define\_excitation(vector)*
- *sarus\_xmt\_define\_virtual\_source(start\_e, end\_e, weights, delays, wavetype, prop\_dir\_focus, use\_fine\_delay)*
- *sarus\_xmt\_define\_virtual\_source\_rc(....)*
- *sarus\_xmt\_set\_emission\_vs(em, virt\_srcs, ha, weights)*

# Receiver setup

- *sarus\_set\_sampling(emissions, start\_d, end\_d, elements\_store, elements\_process)*
- *sarus\_set\_sampling\_rc(emissions, start\_d, end\_d, elements\_store, elements\_process)*
- *sarus\_set\_sampling\_times(emissions, start\_t, end\_t, elements\_store, elements\_process)*
- *sarus\_tgc(emissions, tgc\_vector), 5 / microsec.*
- *sarus\_set\_decimation(dec\_factor, use\_avg)*

# Reading data

- *sarus\_read\_element\_data*(*elements, frame, em*)
- *sarus\_read\_frame\_data*(*frame, st\_em, no\_em...*)
- *sarus\_read\_single\_channel*(*ch\_idx, no\_frm...*)

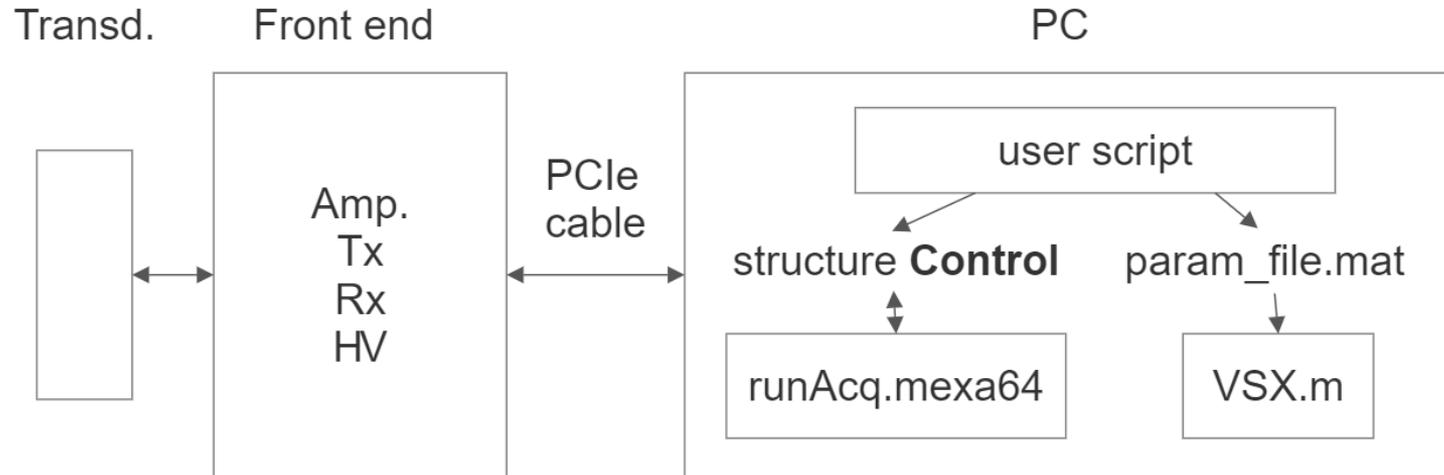
## Saving data

- *sarus\_set\_description\_file*(*file\_name*)
- *sarus\_set\_emission\_types*(*frm\_type, em\_type, fr*)
- *sarus\_set\_scan\_object*(*par\_name, par\_value*)
- *sarus\_save\_data\_set2*(*no\_seq[, path, struct]*)
- *sarus\_compress\_acquisition*(*path*)

# 2020 – Vantage 256



# Vantage control structure



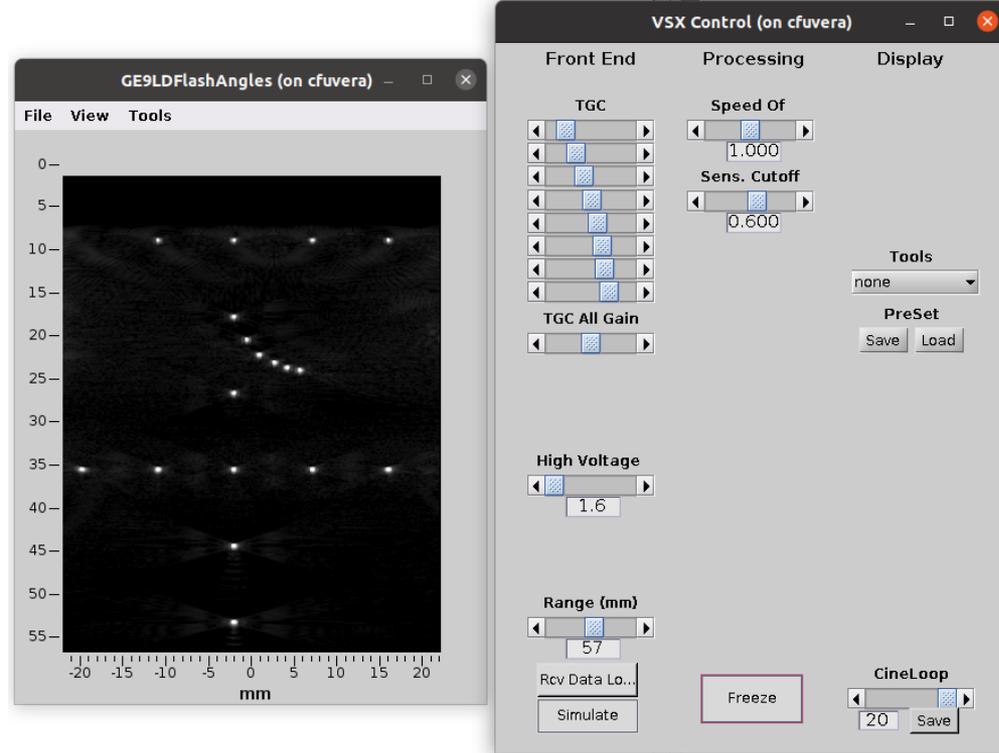
# Vantage setup parameters

- Resource
- Trans
- TW
- TGC
- TX
- Receive
- Event
- SeqControl
- TPC
- PData
- Media
- Recon
- Process
- UI

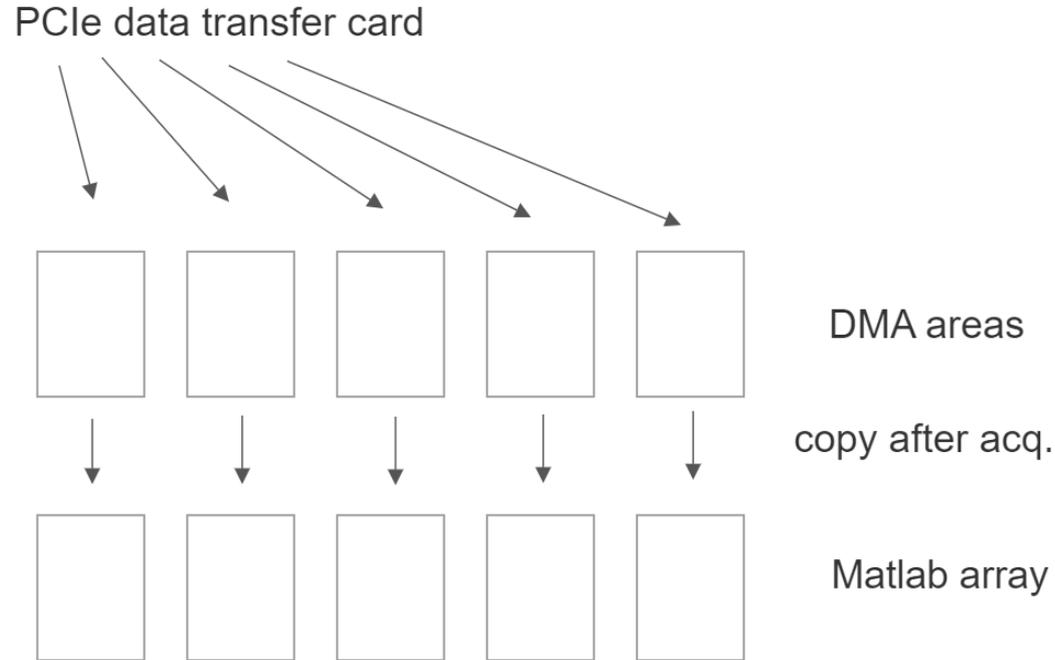
# Vantage interaction/control

- Structure Control:
  - field Command
  - field Parameters

# Vantage GUI (default)



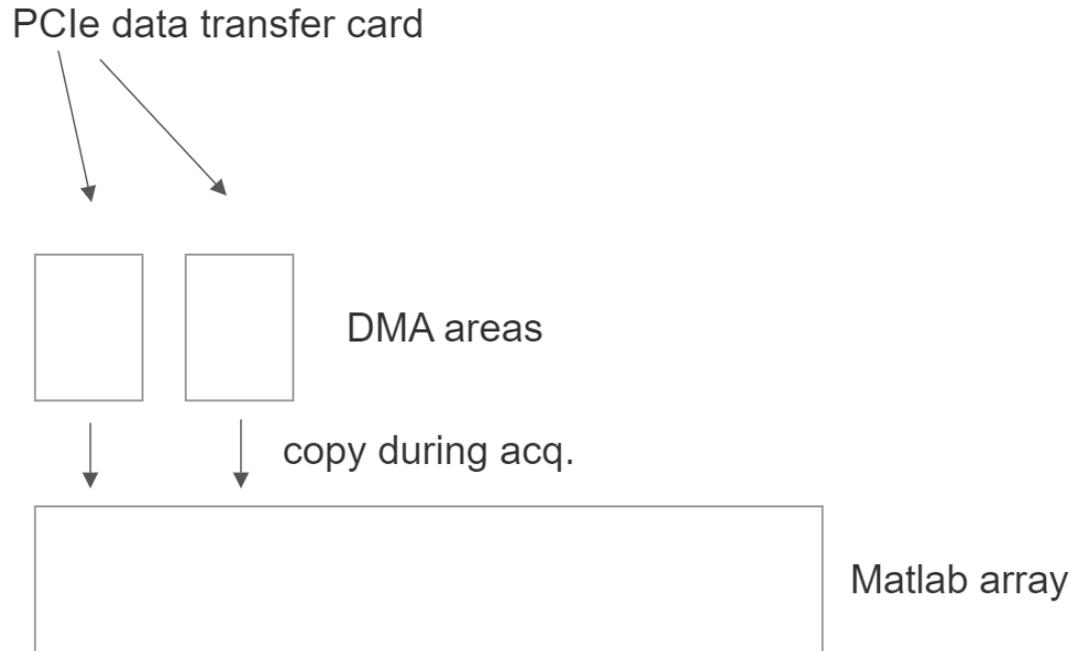
# Vantage data transfer mechanism (default)



# Vantage system hardware limitations

- 132 000 emissions, at  $F_{prf}=5000$  gives 26 seconds
- PC RAM utilization < 50 % with default data transfer mechanism
- DMA transfer size > 64 MB for performance, 2GB max (at CFU: 1.7 GB),
- 3-level transmit
- Tx apodization result not visible
- Tx waveform synthesis has discrete center frequency values
- PC RAM allocation takes 1 sec/GB
- The PC runs a non-real-time OS, GUI operations eat time, disturb acq.

# Vantage data transfer mechanism (CFU)



By idea of Ron Daigle (Verasonics)

# CFU\_scan

Center for Fast Ultrasound Imaging Scan Program (on cfuvera)

Run preview    Adjust TGC    Acquire: Full data set    Acquire: Partial data set    Save data    Image to display    Change acquisition    Quit

Linear B-mode image, rows: Plane x-z  
Frame 6 of 72 frames at t = 0.1920 s

Axial direction - z [mm]

Lateral direction - x [mm]

Linear B-mode image, rows: Plane y-z  
Frame 6 of 72 frames at t = 0.1920 s

Axial direction - z [mm]

Azimuth direction - y [mm]

**Time Gain Compensation**

4 mm    11 mm    17 mm    24 mm    31 mm    37 mm    44 mm

High Voltage: 95 volts

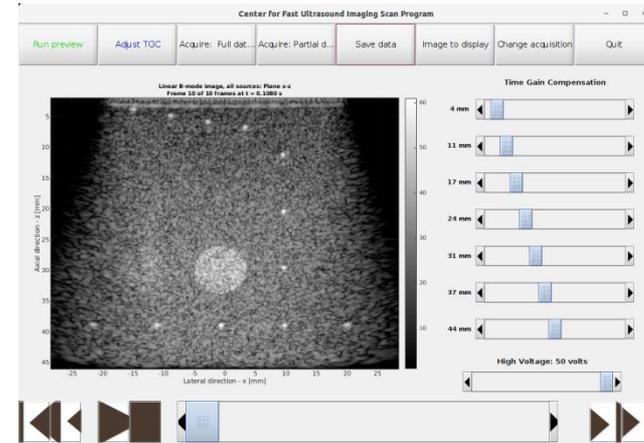
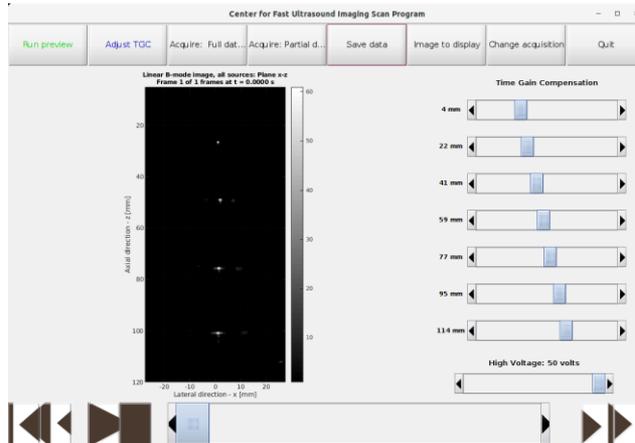
# Scanner parameters

<b>Scanner</b>	<b>2-ch. system</b>	<b>RASMUS</b>	<b>SARUS</b>	<b>Vantage 256</b>	<b>ULA-OP</b>
<i>In use since, year</i>	1991	2000	2010	2020	-
<i>Channels</i>	2	128	1024	256 (x4)	356
<i>Fs, MHz</i>	20	40	70	62.5	78
<i>RAM, GB</i>	7-12 MB	16	128	PC*	80
<i>Throughput, GB/s</i>	0.04	5.12	143.36	3.5 (max. 6.6)	40
<i>Sampling time, s</i>	0.17	3.4	0.9	160*	2
<i>Transmit</i>	-	Linear	Linear	3-level	Linear
<i>Preview</i>	No	Yes	Yes	Yes	Yes (USB 3)
<i>Mobile</i>	Yes	Yes	No	Yes	Yes

\*Vantage PC config. at CFU: 512 GB RAM

# Exercise

- Start CFU\_scan
- Perform a scan of a wire (1 frame) and a tissue phantom (10 frames)
- Save the RF data
- Beamform it using your own beamformer
- Display the images with correct axes and dynamic range of 60 dB.



# How to extract emission data

To extract emission data, use the function:

```
[filtered_samples, t_start, rx_fs, elem_positions, vsrc_position, c] =  
    load_scan_data(path_data, frame_index, em_idx),
```

where the output is:

- `filtered_samples` - RF data with matched filter applied
- `t_start` - start time of the RF data
- `rx_fs` - sampling frequency of the recorded RF data
- `elem_position` - element positions [N x 3], containing X, Y and Z
- `vsrc_position` - position of the virtual source
- `c` - speed of sound in the phantom